Leading order asymptotics for fast diffusions on a bounded domain

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Joint work with

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The model.

We study solutions $w = w(\tau, x) \ge 0$ to the nonlinear diffusion equation or quasilinear heat equation

$$\partial_{\tau}w = \Delta w^m, \quad w(0) = w_0 \ge 0.$$

Depending on the value of m > 0, this is a model for

- diffusion of gas through a porous medium,
- population dynamics,
- gas kinetics,
- diffusion in plasma,
- certain geometric flows.

The archetype model for nonlinear diffusions.

For m > 1, it features slow diffusion:

$$\partial_{\tau} w = \Delta w^m = \nabla \cdot (\underbrace{m \, w^{m-1}}_{\to 0 \text{ as } w \to 0} \nabla w).$$

Degenerate diffusion. Consequence: Finite speed of propagation, i.e., compactly supported solutions remain compactly supported.



Well-posedness and regularity are well understood.

For m < 1, it features fast diffusion:

$$\partial_{\tau} w = \Delta w^m = \nabla \cdot (\underbrace{m w^{m-1}}_{\to \infty \text{ as } w \to 0} \nabla w).$$

Singular diffusion. Consequence: Infinite speed of propagation, i.e., solutions become positive instantaneously.



Well-posedness and regularity are well understood.

Focus in this talk:

Large-time behavior

Large-time dynamics in \mathbb{R}^N .

• Convergence to self-similar Barenblatt solution

$$W(\tau, x) = t^{-N\alpha}V(x/\tau^{\alpha})$$
:

Kamin '73-'76, Friedman–Kamin '80, Kamin–Vázquez '88, Vázquez '03

- Rates of convergence: Carillo-Toscani '00, Otto '01, del Pino-Dolbeault '02, etc.
- Spectral analysis: Zel'dovitch–Barenblatt '58, Denzler–McCann '05, CS '13.
- Asymptotic expansions/Invariant manifolds: Angenent '88, Denzler–Koch–McCann '14, CS '15+, etc.

We impose Dirichlet boundary conditions: w = 0 on $\partial \Omega$.

Convergence to separation-of-variables solution ("friendly giant")

$$W(\tau, x) = \tau^{-\beta} V(x),$$

also sharp rates of convergence: Aronson–Peletier '81, Vázquez '04.

• In particular: $w(\tau) \rightarrow 0$ as $\tau \rightarrow \infty$.

Fast diffusion in bounded domain Ω .

We impose Dirichlet boundary conditions: w = 0 on $\partial \Omega$.

• Extinction in finite time of bounded solutions, $0 \le w \le C$,

 $\exists T = T(w_0)$ such that $w(\tau) \to 0$ as $\tau \uparrow T$,

cf. Sabinina '62, '65, Beryman-Holland '80.

• Convergence to a separation-of-variables solution

$$W(\tau, x) = ((1 - m)(T - \tau))^{\frac{1}{1 - m}} V(x)^{\frac{1}{m}},$$

cf. Berryman-Holland '80, Feireisl-Simondon '00.

 Sharp rates of convergence (at least partial results): for m ∈ (m_c, 1) with m_c = ^{N-2}/_{N+2} by Bonforte–Figalli '21; for m = m_c and radial solutions on a ball: Galaktinov–King '02.

Rescaling.

Large time behavior best understood in rescaled variables. Motivated by separation-of-variables solution,

$$W(\tau, x) = ((1 - m)(T - \tau))^{\frac{1}{1 - m}} V(x)^{\frac{1}{m}},$$

consider

$$w(\tau, x) = ((1 - m)(T - \tau))^{\frac{1}{1 - m}} v(t, x)^{\frac{1}{m}},$$

$$t = \log\left(\frac{T}{T - \tau}\right)^{\frac{m}{m - 1}}, \quad p = \frac{1}{m} > 1,$$

which gives rise to

$$p^{-1}\partial_t v^p - \Delta v = v^p, \quad -\Delta V = V^p.$$

Goal: Find optimal rate of convergence for

$$v(t)
ightarrow V$$
 as $t
ightarrow \infty$.

The stationary problem $-\Delta V = V^{\rho}$ in Ω .

- In general, solutions to elliptic PDE are not unique.
- However, large time limit uniquely determined by initial datum, ∃! V = V(w₀), cf. Feireisl–Simondon '00.
- Formally, a stationary solution is a critical point of the Lyapunov functional

$$\frac{1}{2}\int_{\Omega}|\nabla V|^2\,dx-\frac{1}{p+1}\int_{\Omega}V^{p+1}\,dx.$$

- Sobolev sub-criticality $p < p_c = \frac{1}{m_c} = \frac{N+2}{N-2}$ implies compactness of embedding $W_0^{1,2}(\Omega) \subset L^{p+1}(\Omega)$.
- For p ∈ (1, p_c), stationary solutions satisfy the boundary estimates

$\operatorname{dist}(x,\partial\Omega) \lesssim V(x) \lesssim \operatorname{dist}(x,\partial\Omega).$

• For $p > p_c$, existence of nonnegative bounded solutions may fail.

The relative error $h = \frac{v}{V} - 1$.

Bonforte–Grillo–Vázquez '12: Uniform convergence of relative error:

$$\|h(t)\|_{L^\infty(\Omega)} = \|rac{v(t)-V}{V}\|_{L^\infty(\Omega)} o 0 \quad ext{as } t o \infty.$$

• Change of perspective:

$$\partial_t h + Lh = N[h],$$

with

$$Lh = -V^{-1-p}\nabla \cdot (V^2\nabla h) - (p-1)h,$$

$$N[h] = \underbrace{((1+h)^p - 1 - ph)}_{\lesssim |h|^2} + \underbrace{(1-(1+h)^{p-1})\partial_t h}_{\lesssim |h||\partial_t h|}.$$

Recall: $V(x) \sim \operatorname{dist}(x, \partial \Omega)$, hence *L* becomes singular on $\partial \Omega$:

$$Lh = -\underbrace{V^{1-p}}_{\to\infty}\Delta h - 2\underbrace{V^{-p}}_{\to\infty}\nabla V \cdot \nabla h - (p-1)h.$$

• No boundary conditions!

Understanding the difficulties: The spectrum.

Consider

$$Lh = -V^{-1-p}\nabla \cdot (V^2\nabla h) - (p-1)h.$$

• The operator L has a discrete spectrum on the Hilbert space L^2_{p+1} induced by

$$\|h\|_{L^2_\sigma}^2 = \int_\Omega h^2 \, d\mu_\sigma, \quad d\mu_\sigma = V^\sigma \, dx.$$

• For $h \equiv 1$, it holds that

$$Lh = L1 = 1 - p = (1 - p)h.$$

Hence, there are negative eigenvalues.

It can be proved that 1 - p is the smallest eigenvalue.
 Equivalently, there is no Poincaré inequality of the type

$$\|h\|_{L^2_{p+1}} \leq C \|\nabla h\|_{L^2_2}.$$

Consider linear dynamics

$$\partial_t h + Lh = 0.$$

Then

$$\frac{1}{2}\frac{d}{dt}\int_{\Omega}h^{2}\,d\mu_{p+1}+\int_{\Omega}|\nabla h|^{2}\,d\mu_{2}=(p-1)\int_{\Omega}h^{2}\,d\mu_{p+1}.$$

In the absence of a suitable Poincaré inequality, this identity implies not even decay! We would need

$$c\|h\|_{L^2_{p+1}}^2 \le \|
abla h\|_{L^2_2}^2 \quad ext{with } c > p-1.$$

Note:

$$(p-1) \|h\|_{L^2_{p+1}}^2 = \|\nabla h\|_{L^2_2}^2 \quad \text{iff} \quad h \in \ker L.$$

Main strategy:

- Nonlinear entropy method.
- Restrict to "generic" domains for which ker $L = \{0\}$.
- Convergence in relative error, ||h(t)||_{L∞} → 0, ensures decay of unstable modes.
- Apply improved Poincaré inequality for stable modes.

Theorem (Bonforte–Figalli CPAM '21) If Ω is generic, it holds that

$$\|h(t)\|_{L^2_{p+1}} \lesssim e^{-\lambda_s t},$$

where λ_s is the first positive eigenvalue of L.

Two questions:

What about "non-generic" domains?

AND

Do we know something about higher-order asymptotics?

"Non-generic" domains

Example (Coffman '84, Li '90, Byeon '97, Akagi–Kajikiya '14)

On sufficiently small annuli $\Omega = B_R \setminus B_r$, there exists symmetry breaking (i.e., non-radial) least energy solutions of

$$\frac{1}{2}\int_{\Omega}|\nabla V|^2\,dx-\frac{1}{p+1}\int_{\Omega}V^{p+1}\,dx.$$

Consequence: $\exists \{V_s\}_s$ stationary solutions with $\partial_s|_{s=0} V_s \neq 0$.

$$\implies L(\partial_s|_{s=0} V_s/V_0) = 0.$$

Thus

 $K := \dim \ker L > 0.$

A new approach for arbitrary smooth domains based on a

dynamical systems argument

Theorem (Choi–McCann–CS '21+) It EITHER holds that

$$\|h(t)\|_{L^\infty}\gtrsim \|h(t)\|\gtrsim rac{1}{t} \quad ext{as } t o\infty,$$

OR

$$\|h(t)\|\lesssim \|h(t)\|_{L^\infty}\lesssim e^{-\lambda_{{\scriptscriptstyle {\sf S}}}t}$$
 as $t o\infty.$

2nd result: Integrable kernels

By Bonforte–Figalli '21: If ker $L = \{0\}$, then the convergence is exponentially fast.

This can be extended:

Theorem (Choi–McCann–CS '21+) If the kernel is integrable, then the convergence is exponentially fast.

Definition: A kernel is integrable if for every $\psi \in \ker L$, $\exists \{V_s\}_s$ stationary solutions with $\psi = \partial_s|_{s=0} V_s/V_0 \neq 0$.

The idea of the proof goes back to works by Allard–Almgren '81 and Simon '85 in the context of minimal surfaces and geometric evolution equations.

Theorem (Choi–McCann–CS '21+) If the convergence is exponentially fast, then

$$h(t,x) = \sum_{\lambda_i \in [\lambda_s, 2\lambda_s)} C_i e^{-\lambda_i t} \varphi_i(x) + o\left(e^{-\max_i \lambda_i t}\right),$$

where $L\varphi_i = \lambda_i \varphi_i$ and $\{\varphi_i\}_i$ is orthonormal, $C_i \in \mathbb{R}$.

Idea of the proof of the dichotomy.

Key ingredient 1: New smoothing estimate

Proposition (Choi–McCann–CS '21+) Suppose $||h(t)||_{L^{\infty}} \leq \varepsilon$ for all t. Then, for any $k \in \mathbb{N}_0$ and t > 0, it holds

$$\|\partial_t^k h(t)\|_{L^{\infty}} \leq C(k,t) \|h_0\|_{L^2_{p+1}}.$$

Main consequence: Quadratic estimate on nonlinearity:

$$egin{aligned} \| \mathsf{N}[h(t)] \|_{L^2_{p+1}} \lesssim (\| h(t) \|_{L^\infty} + \| \partial_t h(t) \|_{L^\infty}) \, \| h(t) \|_{L^2_{p+1}} \ &\lesssim \| h(t-1) \|_{L^2_{p+1}} \| h(t) \|_{L^2_{p+1}} \ &\lesssim arepsilon \| h(t) \|_{L^2_{p+1}} \end{aligned}$$

Spectral decomposition.

Orthogonal projection onto stable, center and unstable eigenspaces:

$$h_s = P_s h, \quad h_c = P_c h, \quad h_u = P_u h,$$

 $\partial_t P h + L P h = P N[h].$

Use smoothing estimates to get:

$$\begin{aligned} \frac{d}{dt} \|h_s\| + \underbrace{(\lambda_s - C\varepsilon)}_{>0} \|h_s\| &\leq C\varepsilon \left(\|h_u\| + \|h_c\|\right), \\ & \left|\frac{d}{dt}\|h_c\|\right| \leq C\varepsilon \left(\|h_s\| + \|h_u\| + \|h_c\|\right), \\ \frac{d}{dt}\|h_u\| + \underbrace{(\lambda_u + C\varepsilon)}_{<0} \|h_u\| \geq C\varepsilon \left(\|h_s\| + \|h_c\|\right), \\ \end{aligned}$$
re
$$\begin{aligned} \lambda_u &< 0 \quad \text{largest negative eigenvalue,} \\ \lambda_s &> 0 \quad \text{smallest positive eigenvalue.} \end{aligned}$$

where

Key ingredient 2. Known dynamical systems argument

Unstable modes cannot be active as

 $\|h(t)\| o 0$ as $t \to \infty$

by Bonforte-Grillo-Vázquez '12.

Lemma (Merle–Zaag '98, dichotomy ODE lemma) EITHER

$$\|h_u(t)\|+\|h_s(t)\|=o(\|h_c(t)\|) \quad ext{as } t o\infty,$$

OR

$$\|h_u(t)\|+\|h_c(t)\|=o(\|h_s(t)\|) \quad \text{as } t \to \infty.$$

Remark: Original applied to classify connections between critical points for

$$\partial_t u - \Delta u = u^p.$$

If the stable modes dominate, $\|h(t)\| \lesssim \|h_s(t)\|$:

Starting point:

$$\frac{d}{dt}\|h_s\|+\underbrace{(\lambda_s-C\varepsilon)}_{\stackrel{!}{>}0}\|h_s\|\leq C\varepsilon\left(\|h_u\|+\|h_c\|\right)\leq \tilde{C}\varepsilon\|h_s\|,$$

gives exponential decay,

$$\|h(t)\| \lesssim \|h_s(t)\| \lesssim e^{-\tilde{\lambda}t},$$

if ε is sufficiently small, where 0 $<\lambda_{s}-\tilde{\lambda}\lesssim\varepsilon.$

For optimal rate, iterate

$$\frac{d}{dt}\|h_s\|+\lambda_s\|h_s\|\lesssim \|\mathsf{N}[\mathsf{h}(t)]\|\lesssim \|\mathsf{h}(t-1)\|\|\mathsf{h}(t)\|\lesssim e^{-2\tilde{\lambda}t},$$

and use $2\tilde{\lambda} > \lambda_s$.

If the center modes dominate, $||h(t)|| \leq ||h_c(t)||$:

Starting point:

$$-\frac{d}{dt}\|h_c\| \lesssim \varepsilon \left(\|h_s\| + \|h_u\| + \|h_c\|\right) \lesssim \|h_c\|,$$

so that

$$\|h(t-1)\| \lesssim \|h_c(t-1)\| \lesssim \|h_c(t)\| \le \|h(t)\|.$$

Therefore

$$-\frac{d}{dt}\|h_c\| \leq \|N[h(t)]\| \lesssim \|h(t-1)\|\|h(t)\| \lesssim \|h(t)\|^2 \lesssim \|h_c(t)\|^2,$$

which gives the algebraic lower bound

 $\|h(t)\|\geq \|h_c(t)\|\gtrsim 1/t.$

Comment on the smoothing estimate

Proposition (Choi–McCann–CS '21+)

Suppose $\|h(t)\|_{L^{\infty}} \leq \varepsilon$ for all t. Then, for any $k \in \mathbb{N}_0$ and t > 0, it holds

$$\|\partial_t^k h(t)\|_{L^{\infty}} \leq C(k,t) \|h_0\|_{L^2_{p+1}}.$$

Main steps:

- L_{p+1}^2 -based energy estimates,
- maximal regularity estimates, for $\partial_t h + Lh = f$ with h(0) = 0,

 $\|h\|_{L^{2}(L^{2}_{2p})} + \|\nabla h\|_{L^{2}(L^{2})} + \|\nabla^{2}h\|_{L^{2}(L^{2}_{2})} \lesssim \|f\|_{L^{2}(L^{2}_{2p})},$

- interpolation estimates,
- higher regularity in time and tangential directions,
- Sobolev embedding.

Thank you for your attention.