## Quasi-invariance of Gaussian measures for the 2D Nonlinear Schrödinger equations (joint with Yu Deng, Nikolay Tzvetkov)

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## Nonlinear Schrödinger equations

Nonlinear Schrödinger equations (NLS):

$$i\partial_t u + \Delta u = \pm |u|^{p-1} u, \quad (t,x) \in \mathbb{R} \times \mathbb{T}^d, \ u(t,x) \in \mathbb{C}$$

Conserved Quantities:

$$M[u] = \int_{\mathbb{T}^d} |u|^2 dx, \quad E[u] = \int_{\mathbb{T}^d} \frac{1}{2} |\nabla u|^2 dx \pm \frac{1}{p+1} \int_{\mathbb{T}^d} |u|^{p+1} dx.$$

- Typical expected dynamical properties: Recurrence properties, Energy Cascade?
- Macroscopic description of the flow.
  - ► One way is to equip some "natural" probability measures and study their evolution along the NLS flow on T<sup>d</sup>, which is the main objective of this talk.
  - Sometimes macroscopic properties lead to dynamical consequences. For example, the existence of invariant measures implies the recurrence property of the flow, thanks to Poincaré.

### Gaussian measures

• We will define a Gaussian measure  $\mu_s$ , formally of the form

$$Z^{-1}e^{-\frac{1}{2}\|u\|_{H^s}^2}du=Z^{-1}\exp\left(-\frac{1}{2}\sum_{k\in\mathbb{Z}^d}\langle k\rangle^{2s}|\widehat{u}_k|^2\right)\prod_{k\in\mathbb{Z}^d}d\widehat{u}_k.$$

 The above formal measure can be written as the limit of truncated Gaussian measures

$$\frac{1}{Z_N}\prod_{|k|\leq N}e^{-\frac{1}{2}\langle k\rangle^{2s}|\widehat{u}_k|^2}d\widehat{u}_k.$$

This indicates that μ<sub>s</sub> can be induced by the randomization: Given a probability space (Ω, F, P),

$$\omega \mapsto \phi^{\omega}(x) := \sum_{k \in \mathbb{Z}^d} \frac{g_k(\omega)}{\langle k \rangle^s} e^{ik \cdot x},$$

where  $(g_k(\omega))_{k \in \mathbb{Z}^d}$  are i.i.d. complex Gaussian random variables on  $\Omega$ , with mean 0 and variance 1.

►  $\mu_s$  can be also identified with its covariance operator  $\langle \nabla \rangle^{-2s}$  from  $H^{-s} \mapsto H^s$ .

#### Gaussian measures: sequel

Q: The measure  $\mu_s$  is defined on which space?

• For N < M,

$$\mathbb{E}\Big[\Big\|\sum_{N\leq |k|\leq M}\frac{g_k(\omega)}{\langle k\rangle^s}e^{ik\cdot x}\Big\|_{H^{\sigma}(\mathbb{T}^d)}^2\Big]\sim \sum_{N\leq |k|\leq M}\frac{1}{\langle k\rangle^{2s-2\sigma}}$$

converges if and only if

$$\sigma < \mathbf{s} - \frac{\mathbf{d}}{2}.$$

We conclude that

$$\phi^\omega \in L^2(\Omega; H^\sigma(\mathbb{T}^d))$$

for every  $\sigma < s - \frac{d}{2}$ . So  $\mu_s$  is supported on

$$H^{(s-\frac{d}{2})-} := \bigcap_{\sigma < s - \frac{d}{2}} H^{\sigma}.$$

- Furthermore,  $\mu_s(H^{s-\frac{d}{2}}(\mathbb{T}^d)) = 0$ , in particular,  $\mu_s(H^s) = 0$ .
- ► There is a particular importance for the measure µ<sub>1</sub>, related to the Gibbs measure.

## The Gibbs measure $\Phi_d^{p+1}$ model:

• Defocusing  $\Phi_d^{p+1}$  model corresponds to the Hamiltonian

$$\mathcal{H}[u] = \underbrace{\frac{1}{2} \int_{\mathbb{T}^d} |\nabla u|^2 dx}_{\mathcal{H}_{\mathrm{ki}[u]}} + \underbrace{\frac{1}{p+1} \int_{\mathbb{T}^d} |u|^{p+1} dx}_{V[u]}$$

with formal expression  $e^{-\mathcal{H}[u]}du$ . The Gibbs measure is expected to be defined as  $d\rho(u) = e^{-V[u]}d\mu_1(u)$ , where  $\mu_1 = "e^{-\frac{1}{2}||\nabla u||_{L^2}^2}du''$  is the Gaussian free field.

► The above construction is true only for d = 1, since for d ≥ 2, the support of µ<sub>1</sub> H<sup>(1-d/2)-</sup>(T) misses L<sup>2</sup>(T<sup>d</sup>). For higher dimensions, we need renormalization for V[u] to define the Gibbs measure. The renormalization changes the original Hamiltonian as well as its flow.

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 For the construction, seminar work by: Glimm-Jaffe, Lebowitz-Rose-Speer, Simon, Nelson, Wilson, Aizenman, Barashkov-Gubinelli,....

• 
$$d = 1, 2, \ \Phi_1^{p+1}, \Phi_2^{p+1}$$
 for any  $p \in 2\mathbb{N} + 1$ ;

- $d = 3, \Phi_3^4$  (for other p ??);
- $d \ge 4$ ,  $\Phi_d^{p+1}$  cannot be done for any p (Aizenman, Duminil-Copin).

• Only for d = 1, 2,  $\Phi_d^{p+1}$  is absolutely continuous with respect to  $\mu_1$ .

## Gaussian measures under transformations

### Definition

Given a reversible flow  $\varphi(t)$  and a Gaussian measure  $\mu$  on some Banach space X, we say that  $\mu$  is *quasi-invariant* along  $\varphi(t)$  if  $\varphi(t)_{\#}\mu \ll \mu$  for any  $t \in \mathbb{R}$ .

- At reasonable regularity level (e.x. 1D NLS), invariant Gibbs measure implies that the Gaussian free field μ₁ is quasi-invariant along the NLS flow: the transported measure Φ(t)<sub>#</sub>μ₁ ≪ μ₁ for t ∈ ℝ.
- In the infinite-dimensional space, transported measures become singular easily:
  - Cameron-Martin 1944: Let f ∈ H<sup>σ</sup>(T<sup>d</sup>) and μ<sub>f</sub> be the image of the measure μ<sub>s</sub> under the translation

$$u\mapsto u+f$$

on  $H^{\sigma}$ . Then  $\mu_f \ll \mu_s$  if and only if  $f \in H^s(\mathbb{T}^d)$  for  $s > \sigma + \frac{d}{2}$ . Correspondingly, the Radon-Nikodym density is

$$e^{-\|f\|_{H^s}^2 - (u,f)_{H^s}}$$

 Oh-Sosoe-Tzvetkov: Consider the flowmap φ(t) defined by the ODE i∂<sub>t</sub>u = |u|<sup>2</sup>u. Then for any t ≠ 0, φ(t)<sub>#</sub>μ<sub>s</sub> is singular to μ<sub>s</sub> (s ≥ 1).
 We now consider the specific flow defined by NLS. It turns out that the dispersion can prevents the measure to become singular.

### Main result

Defocusing cubic NLS on  $\mathbb{T}^2$ :

$$i\partial_t u + \Delta u = |u|^2 u, \ (t,x) \in \mathbb{R} \times \mathbb{T}^2, \quad u|_{t=0} = u_0 \in H^{\sigma}.$$

- Scaling critical space H<sup>s<sub>c</sub></sup>(T<sup>2</sup>), s<sub>c</sub> = 0. Locally well-posed in H<sup>σ</sup>, σ > 0 (Bourgain).
- The flowmap Φ(t) is is globally defined on H<sup>σ</sup>, for σ ≥ 1, with the property that (Bourgain, Colliander-Kwon-Oh)

$$\|\Phi(t)u_0\|_{H^{\sigma}(\mathbb{T}^2)} \lesssim \langle t \rangle^{lpha(\sigma)} C(\|u_0\|_{H^{\sigma}}).$$

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#### Theorem (Deng-S.-Tzvetkov, '21-'22)

For  $s \ge 2$ , the Gaussian measure  $\mu_s$  is quasi-invariant along the cubic NLS flow  $\Phi(t)$ .

suppµ<sub>s</sub> = H<sup>(s-1)−</sup>(T<sup>2</sup>) where Φ(t) is globally defined. The required regularity s ≥ 2 is such that on supp(µ<sub>s</sub>), the flow Φ(t) is globally well-defined.

# Comparison for the 2D invariant Gibbs measure problem

Theorem (Bourgain '96, Deng-Nahmod-Yue '19)

There exists a full  $\mu_1$  measure (so full  $\Phi_2^{2m+2}$  measure) set  $\Sigma \subset H^{0-}(\mathbb{T}^2)$ , such that the flow :  $\Phi(t)$  : of the renormalized NLS (Wick-ordered NLS):

$$i\partial_t u + \Delta u =: |u|^{2m} u := "\sum_k e^{ik \cdot x} \Big( \sum_{\substack{k_1 - k_2 + \dots + k_{2m+1} = k \\ no paring: \ k_{2j-1} \neq k_{2j}}} \widehat{u}_{k_1} \overline{\widehat{u}}_{k_2} \cdots \widehat{u}_{k_{2m+1}} \Big)''$$

is well-defined on  $\Sigma.$  Moreover, the Gibbs measure  $\Phi_2^{2m+2}$  is invariant along :  $\Phi(t)$  :

- ► The Wick-ordering is necessary to define the nonlinearity on H<sup>0-</sup> almost surely. Due to the low-regularity nature, the Cauchy problem is very difficult to solve!
- ▶ In an impressive work of DNY, they extend Bourgain's theorem from m = 1 to any m, by introducing the novel Random averaging operator theory to overcome an essential obstruction. Their method inspires many other works.
- ► However, all these invariant Gibbs measure theorems does not provide information on the transport properties for µ<sub>1</sub>, under the real NLS flow.

### Methodology I: Deterministic argument

Here we present several soft-analysis schemes developed in the works of Tzvetkov and: Gunaratnam, Oh, Planchon, Sosoe, Visciglia, Weber, ...

Formally,  $d\mu_s(u) = \frac{1}{Z}e^{-||u||_{H^s}^2}du$ , and we look for a suitable modified energy

$$E_{s}(u) := \|u\|_{H^{s}}^{2} + R_{s}(u) \sim \|u\|_{H^{s}}^{2}$$

and look at the evolution of the measure (after suitable truncation)

$$d\rho_{s}(u) := e^{-R_{s}(u)} d\mu_{s}(u)^{"} = \frac{1}{Z} e^{-E_{s}(u)} du^{"}$$

The Radon-Nikodym density is (if exists) then  $e^{-(E_s(\Phi(t)u)-E_s(u))}$ . Though  $E_s(\Phi(t)u)$  and  $E_s(u)$  are both strongly diverging on  $\operatorname{supp}(\mu_s)$ , the hope is to use some smoothing property (time oscillation) of the dispersive flow.

- Denote by  $G_s(\tau) = \frac{d}{dt} E_s(\Phi(t)u)|_{t=\tau}$ :
  - If we are able to show that

$$\left|\int_{0}^{t}G_{s}(\tau)d\tau\right|\leq C(\mathcal{H}[u])\|u\|_{H^{s-\frac{d}{2}-1}}^{ heta}$$

for some  $\theta$ , then we are done (with the desired density if  $\theta < 2$ , otherwise we need a cutoff for  $||u||_{H^{s-\frac{d}{2}-}}$ ).

### Methodology II: Using the "random oscillation"

The second method is to exploit the random oscillation. Formally, if  $\mu_s(A) = 0$  (hence  $\rho_s(A) = 0$ ), we want to show that  $\rho_s(\Phi(t)A) = 0$ . We compute

$$\frac{d}{dt}\rho_{s}(\Phi(t)A)|_{t=t_{0}}=\frac{d}{dt}\int_{\Phi(t)(A)}d\rho_{s}(u)|_{t=t_{0}}=\int_{A}\frac{d}{dt}e^{-E_{s}(\Phi(t)u)}|_{t=t_{0}}\frac{d}{du},$$

thanks to the Liouville theorem. Recalling that

$$G_s(t_0)=\frac{d}{dt}E_s(\Phi(t)u)|_{t=t_0},$$

the above identity equals to

$$\int_{A} G_{s}(t_{0}) e^{-E_{s}(\Phi(t_{0})u)} du = \int_{\Phi(t_{0})(A)} G_{s}(0) e^{-E_{s}(u)} du.$$

Then by Hölder, we have

$$|rac{d}{dt}
ho_{s}(\Phi(t)A)|_{t=t_{0}}|\leq \|G_{s}(0)\|_{L^{p}(d
ho_{s})}
ho_{s}(\Phi(t_{0})(A))^{1-rac{1}{p}}, \ orall p\geq 2.$$

Then if we are able to show that

$$\|G_s(0)\|_{L^p(\rho_s)} \leq Cp, \ \forall p \geq 2,$$

then by Yudovich-type argument, we deduce that  $\rho_s(\Phi(t)A) \equiv 0$  for any t.

## Modified energy for NLS?

Write

$$v(t) = e^{-it\Delta}u(t), \quad v(t) = \sum_k v_k(t)e^{ik\cdot x}.$$

If u(t) solves  $i\partial_t u + \Delta u = |u|^2 u$ , then

$$\partial_t \mathbf{v}_k = \frac{1}{i} \sum_{k_1 - k_2 + k_3 = k} e^{-it \Phi(\vec{k})} \mathbf{v}_{k_1} \overline{\mathbf{v}}_{k_2} \mathbf{v}_{k_3},$$

where

$$\Phi(\vec{k}) := |k_1|^2 - |k_2|^2 + |k_3|^2 - |k|^2 = 2(k_1 - k_2) \cdot (k_2 - k_3).$$

We have

$$\begin{split} \frac{1}{2} \frac{d}{dt} \| v(t) \|_{H^s}^2 &= -\frac{1}{4} \mathrm{Im} \sum_{\substack{k_1 - k_2 + k_3 - k_4 = 0 \\ k_2 \neq k_1, k_3}} \psi_{2s}(\vec{k}) e^{-it \Phi(\vec{k})} v_{k_1} \overline{v}_{k_2} v_{k_3} \overline{v}_{k_4}, \\ \psi_{2s}(\vec{k}) &= |k_1|^{2s} - |k_2|^{2s} + |k_3|^{2s} - |k_4|^{2s}. \end{split}$$

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### Warming up: 1D analysis

Candidates for the Modified energy can be found by integration by part (Poincaré-Dulac normal form):

$$\sum_{\substack{k_1-k_2+k_3-k_4=0\\k_2\neq k_1,k_3}} \psi_{2s}(\vec{k})e^{-it\Phi(\vec{k})}v_{k_1}\overline{v}_{k_2}v_{k_3}\overline{v}_{k_4} = \partial_t \left(\sum_{\substack{k_1-k_2+k_3-k_4=0\\k_2\neq k_1,k_3}} \frac{\psi_{2s}(\vec{k})}{-i\Phi(\vec{k})}e^{-it\Phi(\vec{k})}v_{k_1}\overline{v}_{k_2}v_{k_3}\overline{v}_{k_4}\right) \\ - \sum_{\substack{k_1-k_2+k_3-k_4=0\\k_2\neq k_1,k_3}} \frac{\psi_{2s}(\vec{k})}{-i\Phi(\vec{k})}e^{-it\Phi(\vec{k})}\partial_t(v_{k_1}\overline{v}_{k_2}v_{k_3}\overline{v}_{k_4})$$

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When d = 1, we have

$$\begin{split} \psi_{2s}(\vec{k}) &= -\Big(\int_0^1 \int_0^1 (\nabla^2 |\cdot|^{2s}) (k_4 + \theta_1 (k_2 - k_3) - \theta_2 (k_1 - k_2)) d\theta_1 d\theta_2 \Big) (k_1 - k_2) \cdot (k_2 - k_3). \\ \text{Thus } |\psi_{2s}(\vec{k})| &\lesssim \max\{|k_1|, |k_2|, |k_3|\}^{2s-2} |\Phi(\vec{k})|. \text{ Then we get, for } s \geq 2, \\ &\frac{d}{dt} \Big( \|v(t)\|_{H^s}^2 + \frac{1}{2} \text{Im} \mathcal{N}_0(v) \Big) \lesssim 1 + \|v(t)\|_{H^{s-1}}^2 \|v(t)\|_{H^{\frac{1}{2}+}}^4. \end{split}$$

► Can be obtained to any nonlinearity p ∈ 2N + 1. There is a nice physical-space based proof by Planchon-Tzvetkov-Visciglia.

## 2D Analysis, the setup

$$\begin{split} \mathcal{N}_{0,t}(\mathbf{v}) &= \sum_{\substack{k_1 - k_2 + k_3 - k_4 = 0 \\ \Phi(\vec{k}) \neq 0}} \psi_{2s}(\vec{k}) \frac{e^{-it\Phi(\vec{k})}}{-i\Phi(\vec{k})} v_{k_1} \overline{v}_{k_2} v_{k_3} \overline{v}_{k_4}, \\ \mathcal{R}_{0,t}(\mathbf{v}) &= \sum_{\substack{k_1 - k_2 + k_3 - k_4 = 0 \\ \Phi(\vec{k}) = 0}} \psi_{2s}(\vec{k}) e^{-it\Phi(\vec{k})} v_{k_1} \overline{v}_{k_2} v_{k_3} \overline{v}_{k_4} \\ \mathcal{R}_{1,1,t}(\mathbf{v}) &= 2 \sum_{\substack{k_1 - k_2 + k_3 - k_4 = 0 \\ \Phi(\vec{k}) \neq 0}} \frac{\psi_{2s}(\vec{k})}{\Phi(\vec{k})} e^{-it\Phi(\vec{k})} \sum_{p_1 - p_2 + p_3 = k_1} e^{-it\Phi(\vec{p})} v_{p_1} \overline{v}_{p_2} v_{p_3} \overline{v}_{k_2} v_{k_3} \overline{v}_{k_4}, \\ \mathcal{R}_{1,2,t}(\mathbf{v}) &= -2 \sum_{\substack{k_1 - k_2 + k_3 - k_4 = 0 \\ \Phi(\vec{k}) \neq 0}} \frac{\psi_{2s}(\vec{k})}{\Phi(\vec{k})} e^{-it\Phi(\vec{k})} \sum_{q_1 - q_2 + q_3 = k_2} e^{it\Phi(\vec{q})} v_{k_1} \overline{v}_{q_1} v_{q_2} \overline{v}_{q_3} v_{k_3} \overline{v}_{k_4}. \end{split}$$

Defining

$$E_{s,t}(v) := \frac{1}{2} \|v\|_{H^s}^2 + \frac{1}{4} \mathrm{Im} \mathcal{N}_{0,t}(v),$$

then along the NLS flow, we have

$$\frac{d}{dt}E_{s,t}(v) := \frac{1}{4} \mathrm{Im} \big[ \mathcal{R}_{1,1,t}(v) + \mathcal{R}_{1,2,t}(v) - \mathcal{R}_{0,t}(v) \big]$$

Let us look at the simplest (resonant) term

$$\mathcal{R}_{0,t}(v) := \sum_{\substack{k_1-k_2+k_3-k_4=0\\ \Phi(\vec{k})=0}} \psi_{2s}(\vec{k}) e^{-it\Phi(\vec{k})} v_{k_1} \overline{v}_{k_2} v_{k_3} \overline{v}_{k_4}.$$

W.L.O.G., we assume that  $v_{k_j} = \widehat{P_{N_j}v}(k_j)$  and  $N_{(1)} \ge N_{(2)} \ge N_{(3)} \ge N_{(4)}$  are the rearrangement of  $N_1, N_2, N_3, N_4$ .

•  $|\psi_{2s}(\vec{k})| \lesssim N_{(1)}^{2s-2} N_{(3)}^2$ .

We have

$$|\mathcal{R}_{0,t}(\nu)| \lesssim N_{(1)}^{2s-2} N_{(3)}^2 \int_0^{2\pi} \int_{\mathbb{T}^2} e^{it\Delta} f_1 \cdot \overline{e^{it\Delta} f_2} e^{it\Delta} f_3 \cdot \overline{e^{it\Delta} f_4} dt dx,$$

where  $\widehat{f}_j(k_j) = |v_{k_j}|$ .

The space-time integral can be treated using the bilinear Strichartz estimate. Due to the unavoidable loss N<sup>0+</sup><sub>(3)</sub>, we have

$$|\mathcal{R}_{0,t}(v)| \lesssim \|\mathbf{P}_{N_{(1)}}v\|_{H^{s-1}} \|\mathbf{P}_{N_{(2)}}v\|_{H^{s-1}} \|\mathbf{P}_{N_{(3)}}v\|_{H^{2+}} \|\mathbf{P}_{N_{(4)}}v\|_{L^{2}}.$$

No matter how large s is, the above estimate is not enough for our need, as v ∈ H<sup>(s-1)−</sup> almost surely. Nevertheless, we are ε-close to what we expect (for s large).

### Exploiting the random oscillation

By Method II, what we are allowed reduce the estimate to t = 0 and average on the support of the measure. So we have access to the probability toolbox: Wiener chaos estimate: *I*-linear Gaussian sum:

$$\mathcal{T}_I := \sum_{k_1,\cdots,k_l} c_{k_1,\cdots,k_l} g_{k_1}^{\pm}(\omega) \cdots g_{k_l}^{\pm}(\omega),$$

for any  $p \geq 2$ ,

$$\|\mathcal{T}_I\|_{L^p_{\omega}} \leq Cp^{\frac{1}{2}} \|\mathcal{T}_I\|_{L^2_{\omega}}.$$

► The pairing contributions (k<sub>1</sub> = k<sub>2</sub>, k<sub>3</sub> = k<sub>4</sub>), (k<sub>1</sub> = k<sub>4</sub>, k<sub>2</sub> = k<sub>3</sub>) in *R*<sub>0,t</sub>(v) disappear by taking the imaginary part, it is reduced to estimate

$$p^{2} \bigg\| \sum_{\substack{k_{1}-k_{2}+k_{3}-k_{4}=0,\\k_{2}\neq k_{1},k_{3}\\\Phi(\vec{k})=0}} \psi_{2s}(\vec{k}) \mathbf{1}_{|k_{j}|\sim N_{j}} \frac{g_{k_{1}}(\omega)\overline{g}_{k_{2}}(\omega)g_{k_{3}}(\omega)\overline{g}_{k_{4}}(\omega)}{\langle k_{1}\rangle^{s}\langle k_{2}\rangle^{s}\langle k_{3}\rangle^{s}\langle k_{4}\rangle^{s}} \bigg\|_{L^{2}_{\omega}}$$

- ► Consider the worst case, say  $N_1 \sim N_2 \gg N_3 + N_4 = O(1)$ , the above quantity can be crudely bounded by  $p^2 N_{(1)}^{2s-2} \cdot N_{(1)}^{-2s+1} = p^2 N_{(1)}^{-1}$ .
- By interpolating with the deterministic bound in the last slide, we conclude that ||ImR<sub>0,t</sub>(v)|<sub>t=0</sub>||<sub>L<sup>p</sup><sub>w</sub></sub> ≤ Cp.

- ► The treatment for  $\mathcal{N}_{0,t}(v)$  follows from the similar analysis + resonance decomposition according to the value of  $\Phi(\vec{k})$ .
- ► However, the estimate for the second generations R<sub>1,j,t</sub>(v), j = 1, 2 requires another algebraic cancellation.
- The reason is that in the high-high-low-low-low-low regime, the most problematic contribution is the paring of two dominant frequencies living in different generations. These types of pairing prevent us to gain from the Winer chaos.

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For example, in  $\mathcal{R}_{1,1,t}(v)$ , there are two types of pairings:



Paring the leaves l', l'' Paring t

Paring the leaves l', l''

### Key cancellation (Sequel)

Written in formula, these two pairing configurations are:

$$\begin{split} \mathcal{S}_{1,1,1}(v) &:= 4 \sum_{k_1 \neq k_2} |v_{k_2}|^2 \sum_{\substack{|k_3| + |k_4 \ll |k_1|, |k_2| \\ |p_2| + |p_3| \ll |k_1|, |k_2| \\ k_3 - k_4 = k_2 - k_1 \\ p_2 - p_3 = k_2 - k_1 }} \frac{\psi_{2s}(\vec{k})}{\Phi(\vec{k})} e^{-it(|k_3|^2 - |k_4|^2 + |p_2|^2 - |p_3|^2)} v_{k_3} \overline{v}_{k_4} \overline{v}_{p_2} v_{p_3} \\ (1) \\ \mathcal{S}_{1,1,2}(v) &:= 4 \sum_{k_1, k_3} \frac{|v_{k_3}|^2}{|k_2| + |k_4| \ll |k_1|, |k_3|} \frac{\psi_{2s}(\vec{k})}{\Phi(\vec{k})} e^{it(|k_2|^2 + |k_4|^2 - |p_1|^2 - |p_3|^2)} \overline{v}_{k_2} \overline{v}_{k_4} v_{p_1} v_{p_3}. \end{split}$$

,

To understand the hidden cancellation, for  $S_{1,1,1}(v)$ , one can think about the sum is taken over  $|k_3|, |k_4|, |p_2|, |p_3| = O(1)$ , then

$$\frac{\psi_{2s}(\vec{k})}{\Phi(\vec{k})} \approx \frac{|k_1|^{2s} - |k_2|^{2s}}{|k_1|^2 - |k_2|^2},$$

then the second sum in the definition of  $S_{1,1,1}$  is completely decoupled as  $|\cdots|^2$  and we deduce that  $S_{1,1,1}$  is almost real.

### Final remarks

- In work in progress with Y. Deng and N. Tzvetkov for the 3D NLS as well.
- For the moment, we do not know how much regularity we need to ensure the quasi-invariance property, especially in situations where we only have probabilistic well-posedness for the flow.
- What can we say about the Radon-Nikodym density? More philosophically, is there any link to the energy cascade phenomenon?

# Thank you for your attention !